Lecture 26 Let us fir st note that this model we con structed above is known as the can ornical model. We one now ready to prove the following. M, w F q iff q E w, where M is the canonical model. (Truth lemma) Once we have the truth lemma, we which gives us a pointed model (M, Δ) for Δ , and hence a pointed model (M, Δ) for M as $\Delta \geq M$. Proof of the buth lemma We knove this by applying induction on the size of Q.

Base case: Q:= | The result follows from the definition of V. M, w = p ill we V(b) iff pew. I.H. Suppose the result holds for all formulas q of size < m. J.S. Suppose Q is a formula of size m + 1. Then we have the following cases φ:= 7 Ψ · M, ω Ε 7 Ψ iff M, ω Η Ψ iff Ψ ε ω (IH)

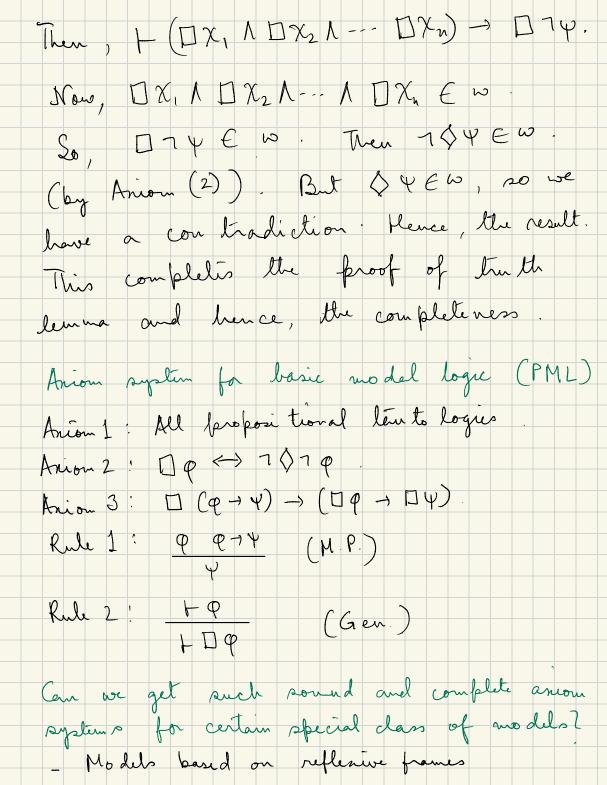
Iff 7 Ψ ε ω (MCS). So, M, ω F φ iff φ ε ω. φ = YVX M, ω = YVX iff M, ω = Y on, M, ω = X, iff YEW or, XEW (I.H.) iff YVXEW (MCS) So, M, W F Q H Q E W. Q : De have to show that M, w = & y iff & y & w. Suppose M, w F QY. To alow QY EW Since M, w \ \Quad \ \Quad \ \Quad \ \Quad \ \Quad \ \Quad \ \ \Quad \Quad \ \Quad \Quad \ \Quad \ \Quad \

there is v in y with who and yev. Then, by definition of R, QYEW. Conversely, suppose that & y E w. To show that M, w F & y. We have to show that there is v in I such that wko and M, v F y (by I-H., M, v F y ill y E v). So, we have to find a v in My such that w Rv and y Ev. Thus our assumption is & y E w. And, we med to show the enistence of a v such that yeu and for all modal formulas

q, qe implies & qe by Let us first prove the following Observation. WR v iff for all modal formules Q, DQE w implies QE V. Proof: A Suppose w Rv. Let q be a and dal formula such that DQE w. To show QEU. Suppose not. Thum, 7 QEU. So \$70 E w.

Anion 2 19 0 7079 Then 7 \$\overline{1} \text{\$\text{\$\phi\$}} \text{\$\text{\$\phi\$}\$ (Check !) This is a contradiction to the consistency of w So we have our result, that is, QEV. Thus for all model for mulas Q, whenever DQ Ew, Q & v. model formulas Q, DQEW implies QEV. To show that wo kv, that is, for all model formula q, Q ∈ v implies Q Q ∈ w Let Q ∈ v. To show Q ∈ w. Suppose not Then, 7\$ Q ∈ w. Then, by Anion (2), D7QEW (Check). Then, 7000, a contradiction. Hence, the result This completes the proof of the observation proof. We have: SYEW We need to about existence of an MCS & such that is Ru Let $v' = \{v\} \cup \{x : \Box x \in \omega\}$ is enough to show that o' is

consistent. Because then, we can take vo to be an MCS estimating v'. Such a vould patrisfy both the conditions yeu Proof of v' being consistent Suppose not. Then there exists a finite subset of v that is inconsistent. So, there are $\chi_1, \chi_2, \dots, \chi_n$, such that Ex, Xz, -... Xn3 + 7 y (Check!) [H.W. If MUZQ] is inconsistent, then M+79] Then, $\vdash (\chi, \Lambda \chi_2 \Lambda \cdots \Lambda \chi_n) \rightarrow \tau_{\psi}$. [Rule (2): +Q (Generali action)] Then, $\vdash \square((X, \Lambda X_2 \Lambda - - \Lambda X_n) \rightarrow \forall)$ [Aniom (3): [(P)+) - ([P] - [V)] Thun, - - - (x, 1 x21 -- 1 xn) -> 074. $: \square(\varphi \wedge \psi) \leftrightarrow (\square \varphi \wedge \square \psi) (HW) \rceil$



- Models based on transitive frames - Models based on symmetric frames - Models based on equivalence frames In the proof above, we showed that rtp iff rtp. For defining = we considered all kripke models. Now we can consider some restricted class of models like above Examples 1. Reflerive models: What would be the corresponding anion The proof idea follows from the completeness

sproof that we finished just now, but for

this case we need to ensure that the

canonical model is reflexive, that is R should have the property: who for all wew, the set of all MCS's. This me ans that for all modal for nulas φ , $\varphi \in \omega$ implies $\Diamond \varphi \in \omega$ (equivalently,

D φ ∈ ω implies φ ∈ ω). Ariom T: DQ -> Q. Thus, the assion system for PML Aniom T will give us a complete axion atignation for the models based on reflexive frames 2. Transitive models Anion 4: De > DDe Then, the arrow system for PML bill give us a complete anionatization for the models based on transitive frames Some other examples. 1. System K (all models) 2. System T (reflerive models) 3. System 34 (reflexive and transitive models)
4. System 35 (models with equivalence relations)